Preface

This book provides an introduction both to real analysis and to a range of important applications that depend on this material. Three-fifths of the book is a series of essentially independent chapters covering topics from Fourier series and polynomial approximation to discrete dynamical systems and convex optimization. Studying these applications can, we believe, both improve understanding of real analysis and prepare for more intensive work in each topic. There is enough material to allow a choice of applications and to support courses at a variety of levels.

This book is a substantial revision of *Real Analysis with Real Applications*, which was published in 2001 by Prentice Hall. The major change in this version is a greater emphasis on the latter part of the book, focussed on applications. A few of these chapters would make a good second course in real analysis through the optic of one or more applied areas. Any single chapter can be used for a senior seminar.

The first part of the book contains the core results of a first course in real analysis. This background is essential to understanding the applications. In particular, the notions of limit and approximation are two sides of the same coin, and this interplay is central to the whole book. Several topics not needed for the applications are not included in the book but are available online, at both this book's official website www.springer.com/978-0-387-98097-3 and our own personal websites, www.math.uwaterloo.ca/~krdavids/ and www.math.unl.edu/~adonsig1/.

The applications have been chosen from both classical and modern topics of interest in applied mathematics and related fields. Our goal is to discuss the theoretical underpinnings of these applied areas, showing the role of the fundamental principles of analysis. This is not a methods course, although some familiarity with the computational or methods-oriented aspects of these topics may help the student appreciate how the topics are developed. In each application, we have attempted to get to a number of substantial results, and to show how these results depend on the theory.

This book began in 1984 when the first author wrote a short set of course notes (120 pages) for a real analysis class at the University of Waterloo designed for students who came primarily from applied math and computer science. The idea was to

viii Preface

get to the basic results of analysis quickly, and then illustrate their role in a variety of applications. At that time, the applications were limited to polynomial approximation, Newton's method, differential equations, and Fourier series.

A plan evolved to expand these notes into a textbook suitable for a one- or twosemester course. We expanded both the theoretical section and the choice of applications in order to make the text more flexible. As a consequence, the text is not uniformly difficult. The material is arranged by topic, and generally each chapter gets more difficult as one progresses through it. The instructor can omit some more difficult topics in the early chapters if they will not be needed later.

We emphasize the role of normed vector spaces in analysis, since they provide a natural framework for most of the applications. So some knowledge of linear algebra is needed. Of course, the reader also should have a reasonable working knowledge of differential and integral calculus. While multivariable calculus is an asset because of the increased level of sophistication and the incorporation of linear algebra, it is not essential. Some of this background material is outlined in the review chapter.

By and large, the various applications are independent of each other. However, there are references to material in other chapters. For example, in the wavelets chapter (Chapter 15), it seems essential to make comparisons with the classical approximation results for Fourier series and for polynomials.

It is possible to use an application chapter on its own for a student seminar or topics course. We have included several modern topics of interest in addition to the classical subjects of applied mathematics. The chapter on discrete dynamical systems (Chapter 11) introduces the notions of chaos and fractals and develops a number of examples. The chapter on wavelets (Chapter 15) illustrates the ideas with the Haar wavelet. It continues with a construction of wavelets of compact support, and gives a complete treatment of a somewhat easier continuous wavelet. In the final chapter (Chapter 16), we study convex optimization and convex programming. Both of these latter chapters require more linear algebra than the others.

We would like to thank various people who worked with early versions of this book for their helpful comments, in particular, Robert André, John Baker, Jon Borwein, Ola Bratteli, Brian Forrest, John Holbrook, Stephen Krantz, Michael Lamoureux, Leo Livshits, Mike McAsey, Robert Manning, John Orr, Justin Peters, Gabriel Prajitura, David Seigel, Ed Vrscay, and Frank Zorzitto. We also thank our students Geoffrey Crutwell, Colin Davidson, Sean Desaulniers, Masoud Kamgarpour, Michael Lipnowski, and Alex Wright for working through parts of the book and solving many of the exercises. We also thank the students in various classes at the University of Waterloo and at the University of Nebraska, where early versions of the text were used and tested.

We welcome comments on this book.

Waterloo, ON & Lincoln, NE March, 2009

Kenneth R. Davidson Allan P. Donsig

Contents

Part A Analysis

1	Review		
	1.1	Calculus	3
	1.2	Linear Algebra	5
	1.3	Appendix: Equivalence Relations	7
2	The Real Numbers		
	2.1	An Overview of the Real Numbers	9
	2.2	The Real Numbers and Their Arithmetic	10
	2.3	The Least Upper Bound Principle	13
	2.4	Limits	15
	2.5	Basic Properties of Limits	19
	2.6	Monotone Sequences	20
	2.7	Subsequences	
	2.8	•	
	2.9	Countable Sets	
3	Series		
	3.1	Convergent Series	35
	3.2	Convergence Tests for Series	
	3.3	Absolute and Conditional Convergence	

X	Contents

4	Торо	ology of \mathbb{R}^n	48	
	4.1	<i>n</i> -Dimensional Space		
	4.2	Convergence and Completeness in \mathbb{R}^n	52	
	4.3	Closed and Open Subsets of \mathbb{R}^n	56	
	4.4	Compact Sets and the Heine–Borel Theorem	61	
5	Fun	ctions	67	
	5.1	Limits and Continuity	67	
	5.2	Discontinuous Functions	72	
	5.3	Properties of Continuous Functions	77	
	5.4	Compactness and Extreme Values	80	
	5.5	Uniform Continuity	82	
	5.6	The Intermediate Value Theorem	88	
	5.7	Monotone Functions	90	
6	Diffe	erentiation and Integration	94	
	6.1	Differentiable Functions	94	
	6.2	The Mean Value Theorem	99	
	6.3	Riemann Integration	103	
	6.4	The Fundamental Theorem of Calculus	109	
7	Norms and Inner Products			
	7.1	Normed Vector Spaces		
	7.2	Topology in Normed Spaces	117	
	7.3	Finite-Dimensional Normed Spaces		
	7.4	Inner Product Spaces	124	
	7.5	Finite Orthonormal Sets	128	
	7.6	Fourier Series		
	7.7	Orthogonal Expansions and Hilbert Spaces	136	
8	Lim	its of Functions		
	8.1	Limits of Functions		
	8.2	Uniform Convergence and Continuity	147	
	0.2			
	8.3	Uniform Convergence and Integration		
			150	
	8.3	Uniform Convergence and Integration	150 154	
	8.3 8.4	Uniform Convergence and Integration	150 154 161	
9	8.3 8.4 8.5 8.6	Uniform Convergence and Integration	150 154 161 168	
9	8.3 8.4 8.5 8.6 Met 9.1	Uniform Convergence and Integration Series of Functions Power Series Compactness and Subsets of $C(K)$ ric Spaces Definitions and Examples	150 154 161 168 175 175	
9	8.3 8.4 8.5 8.6 Met	Uniform Convergence and Integration Series of Functions Power Series Compactness and Subsets of $C(K)$ ric Spaces	150 154 161 168 175 175	

Contents xi

Part B	Applications
--------	--------------

10	Appro	oximation by Polynomials
	10.1	Taylor Series
	10.2	How Not to Approximate a Function
	10.3	Bernstein's Proof of the Weierstrass Theorem
	10.4	Accuracy of Approximation
	10.5	Existence of Best Approximations
	10.6	Characterizing Best Approximations
	10.7	Expansions Using Chebyshev Polynomials
	10.8	Splines
	10.9	Uniform Approximation by Splines
	10.10	The Stone–Weierstrass Theorem
11	Discre	ete Dynamical Systems240
	11.1	Fixed Points and the Contraction Principle
	11.2	Newton's Method
	11.3	Orbits of a Dynamical System
	11.4	Periodic Points
	11.5	Chaotic Systems
	11.6	Topological Conjugacy
	11.7	Iterated Function Systems
12	Differ	rential Equations
	12.1	Integral Equations and Contractions
	12.2	Calculus of Vector-Valued Functions
	12.3	Differential Equations and Fixed Points
	12.4	Solutions of Differential Equations
	12.5	Local Solutions
	12.6	Linear Differential Equations
	12.7	Perturbation and Stability of DEs
	12.8	Existence Without Uniqueness
13	Fouri	er Series and Physics
10	13.1	The Steady-State Heat Equation
	13.2	Formal Solution
	13.3	Convergence in the Open Disk
	13.4	The Poisson Formula
	13.5	Poisson's Theorem
	13.6	The Maximum Principle
	13.7	The Vibrating String (Formal Solution)
	13.7	The Vibrating String (Rigorous Solution)
	13.9	Appendix: The Complex Exponential
	13.7	Appendia, The Complex Exponential

xii	Contents
-----	----------

14	Fouri	er Series and Approximation
	14.1	The Riemann–Lebesgue Lemma
	14.2	Pointwise Convergence of Fourier Series
	14.3	Gibbs's Phenomenon
	14.4	Cesàro Summation of Fourier Series
	14.5	Least Squares Approximations
	14.6	The Isoperimetric Problem
	14.7	Best Approximation by Trigonometric Polynomials 390
	14.8	Connections with Polynomial Approximation
	14.9	Jackson's Theorem and Bernstein's Theorem
15	Wave	lets
	15.1	Introduction
	15.2	The Haar Wavelet
	15.3	Multiresolution Analysis
	15.4	Recovering the Wavelet
	15.5	Daubechies Wavelets
	15.6	Existence of the Daubechies Wavelet
	15.7	Approximations Using Wavelets
	15.8	The Franklin Wavelet
	15.9	Riesz Multiresolution Analysis
16	Conve	exity and Optimization449
	16.1	Convex Sets
	16.2	Relative Interior
	16.3	Separation Theorems
	16.4	Extreme Points
	16.5	Convex Functions in One Dimension
	16.6	Convex Functions in Higher Dimensions
	16.7	Subdifferentials and Directional Derivatives
	16.8	Tangent and Normal Cones
	16.9	Constrained Minimization
	16.10	The Minimax Theorem
Ref	ference	s505
Index		